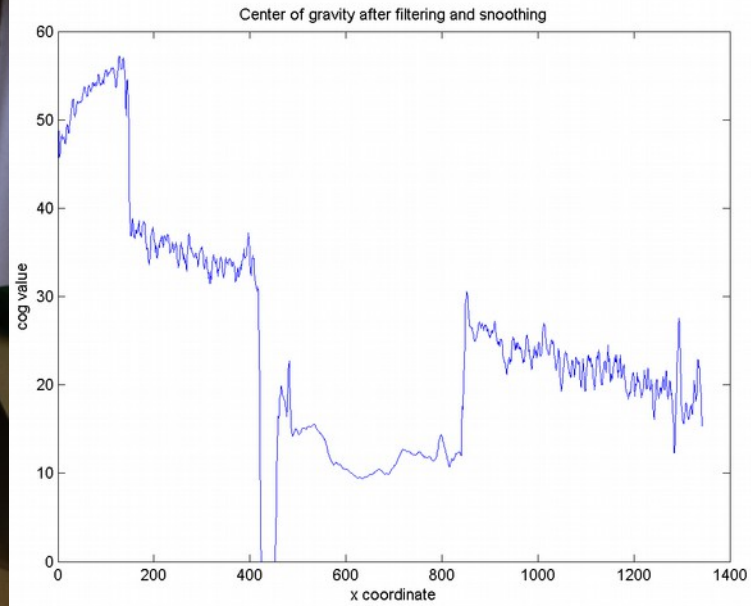
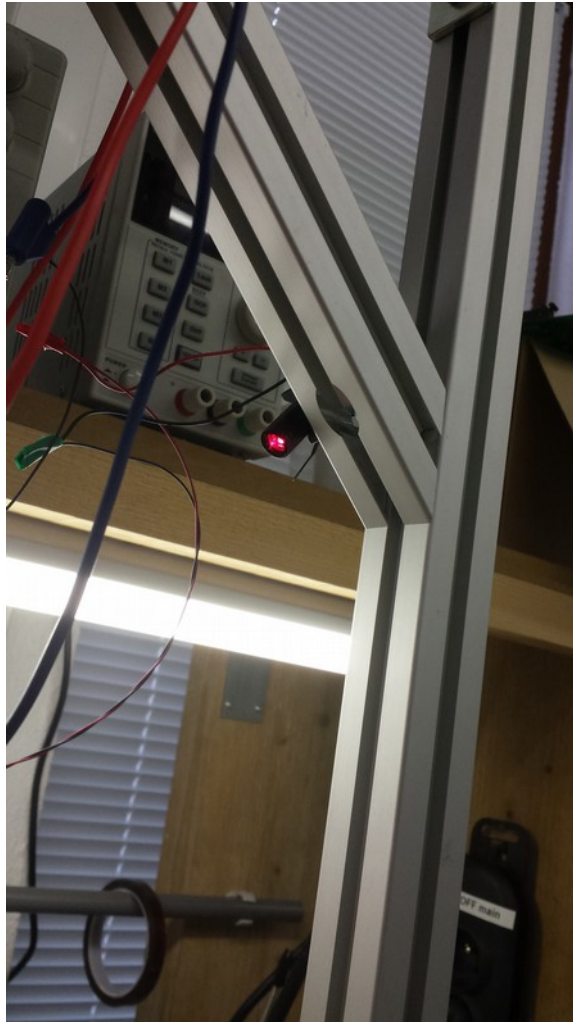
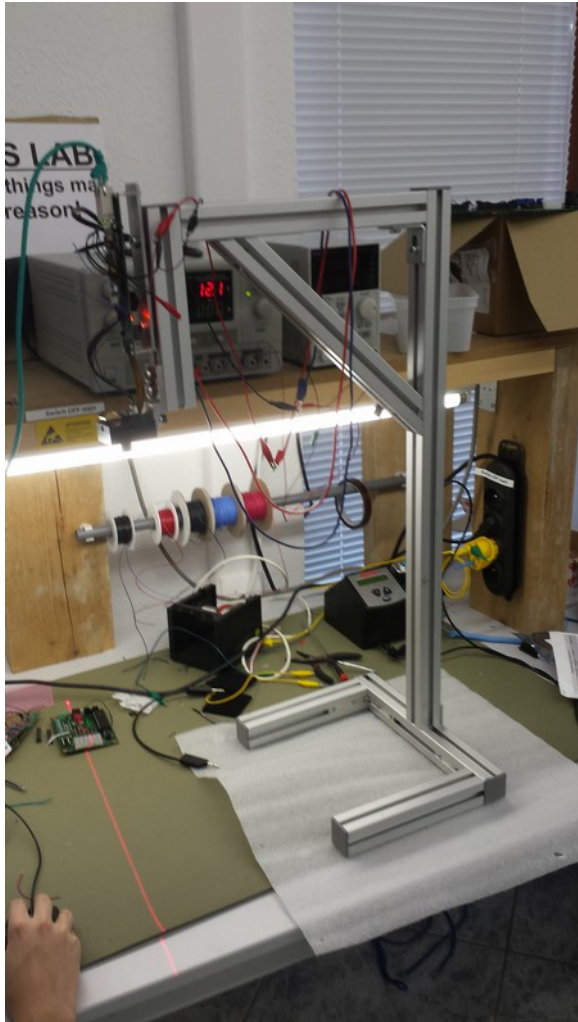


Structured Light 3D



Structured light 3D



Stereo Vision

- Look for shift in left image compared to right image (disparity) $d = dl - dr$ with an ideal distance resolution of $\Delta r = \frac{r^2}{bf} \Delta d$ except in the blind spot between the sensors, too close to the system

